

A paradigm for interval-aware programming

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March 1, 2023 · Conference for Next Generation Arithmetic (CoNGA) 2023, Singapore

Motivation

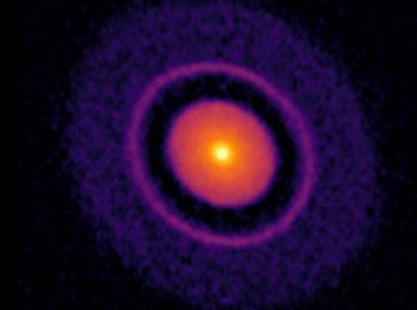
Study protoplanetary growth with a stochastic representative particle method.

Problem:

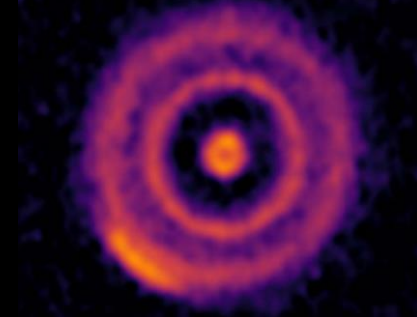
n particles $\rightarrow n^2$ matrix of interaction rates:

$$\begin{bmatrix} \lambda_{11} & \lambda_{12} & \lambda_{13} & \cdots & \lambda_{1n} \\ \lambda_{21} & \lambda_{22} & \lambda_{23} & \cdots & \lambda_{2n} \\ \lambda_{31} & \lambda_{32} & \lambda_{33} & \cdots & \lambda_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \lambda_{n1} & \lambda_{n2} & \lambda_{n3} & \cdots & \lambda_{nn} \end{bmatrix}$$

Elias 24



HD 143006



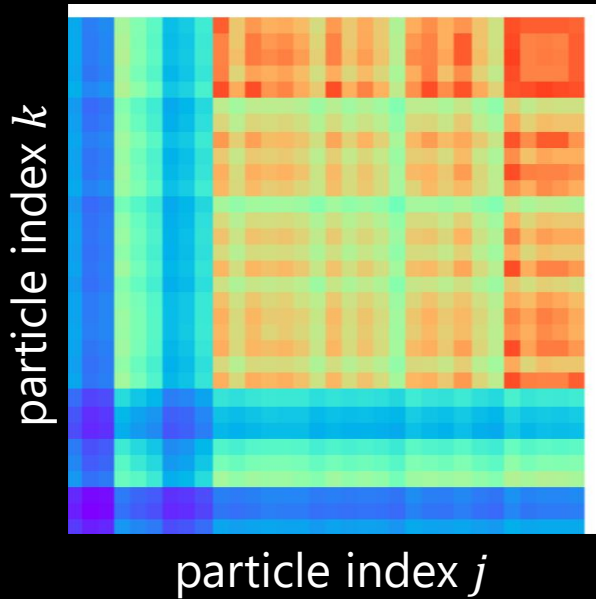
dust rings observed by DSHARP survey, reproduced from Andrews et al., 2018 [1]

Bucketing

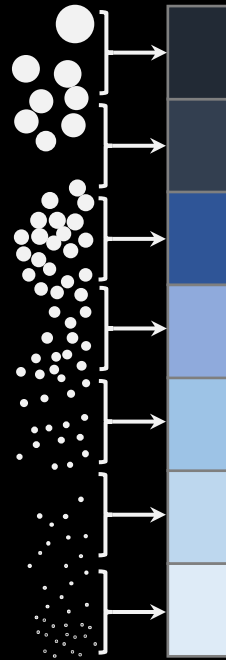
Beutel et al., in prep.

interaction rates

$$\lambda_{jk} := \lambda(\mathbf{q}_j, \mathbf{q}_k)$$

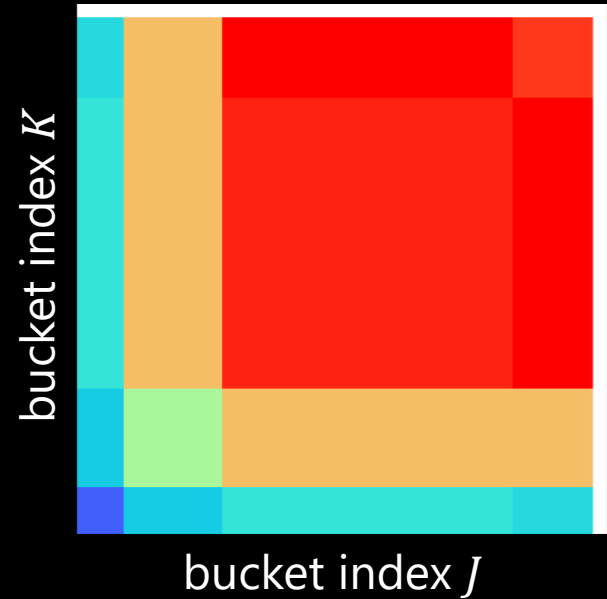


group particles
in buckets



interaction rate bounds

$$\Lambda_{JK} := \Lambda(\mathbf{Q}_J, \mathbf{Q}_K)$$



Set arithmetic

Arithmetic operations can be defined for set-valued arguments.

$$\sin [0, \pi) = [0, 1]$$

$$f(\mathcal{S}) := \{f(x) \mid x \in \mathcal{S}\}$$

(*set extension*)

Interval arithmetic

interval notation:
 $X \equiv [X^-, X^+]$

Arithmetic operations can be defined for intervals.

Examples:

$$A + B := [A^- + B^-, A^+ + B^+]$$

$$-A := [-A^+, -A^-]$$

$$\sqrt{A} := [\sqrt{A^-}, \sqrt{A^+}]$$

$$[5,7] + [0,1] = [5,8]$$

$$-[0,1] = [-1,0]$$

$$\sqrt{[4,9]} = [2,3]$$

(*'interval extensions'*)

'Fundamental Theorem of Interval Arithmetic'

Let a function

$$f: \mathbb{R} \rightarrow \mathbb{R}, x \mapsto f(x)$$

be composed of interval-extensible operations.

Construct a function  *set of all intervals in \mathbb{R}*


$$F: [\mathbb{R}] \rightarrow [\mathbb{R}], X \mapsto F(X)$$

by replacing operations with their interval extensions.


Then, F is an *interval extension* of f :

$$\forall X \in [\mathbb{R}] \forall x \in X: f(x) \in F(X).$$

say,


$$f(x) = x^2 - 2x$$
$$f(x) = (x - 1)^2 - 1$$

algebraically equivalent


$$F(X) = X^2 - 2X$$
$$F(X) = (X - 1)^2 - 1$$

better results
(tighter intervals)

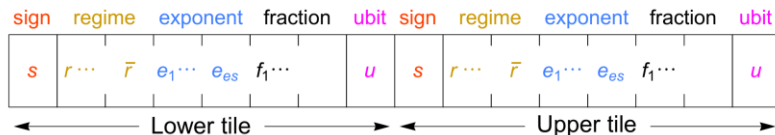
→ dependency problem

Posits and valids

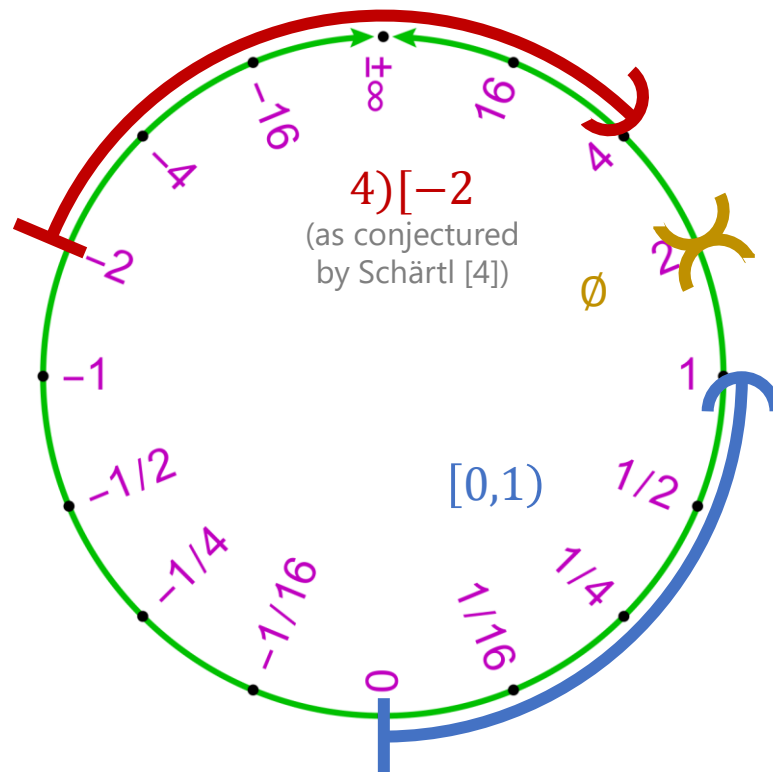
Posits were originally accompanied by *valids*:

Gustafson & Yonemoto, 2017 [2]

- posit arithmetic (and IEEE 754 floats): non-rigorous but fast
- valid arithmetic (and interval arithmetic): more expensive, but rigorous bounds



illustrations reproduced from Gustafson, 2017 [3], annotations mine



Goal:
'two modes of operation, selectable by the user'

Gustafson, 2017 [3]

Interval-aware code

$$f(x) = (x - 1)^2 - 1$$

```
template <typename T>  
T f(T x) {  
    return square(x - 1) - 1;  
}
```

```
auto x = 1.;  
auto y = f(x); // -1
```

```
auto X = Interval{ 0, 1 }; // [0,1]  
auto Y = f(X); // [-1,0]
```

```
auto p = Posit(1);  
auto q = f(p); // -1
```

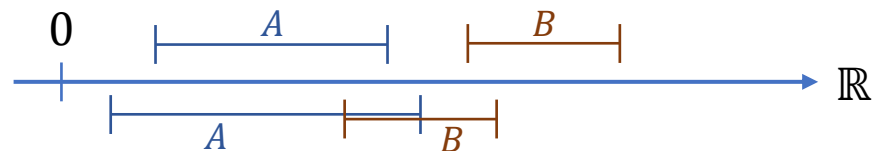
```
auto V = Valid{ 0,open, 0,open }; // ∅  
auto W = f(V); // ∅
```


Interval-aware code with branches

$$\max(a, b) := \begin{cases} b & \text{if } a < b \\ a & \text{otherwise} \end{cases}$$

What could ' $A < B$ ' mean for sets A, B ?

- $\forall a \in A, b \in B: a < b$
- $\exists a \in A, b \in B: a < b$

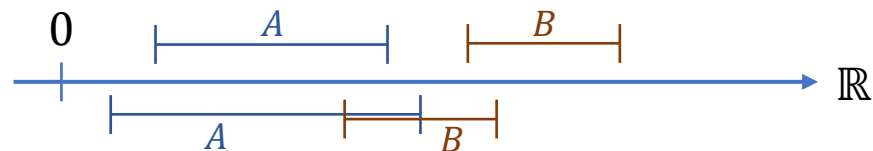


Interval-aware code with branches

$$\max(a, b) := \begin{cases} b & \text{if } a < b \\ a & \text{otherwise} \end{cases}$$

What could ' $A < B$ ' mean for sets A, B ?

- 'certainly $A < B$ '
- 'possibly $A < B$ '



Implementing max

$$\max(a, b) := \begin{cases} b & \text{if } a < b \\ a & \text{otherwise} \end{cases}$$

```

template <typename T>
T max(T a, T b) {
    T x;
    if (a < b) {
        x = b;
    }
    else {
        x = a;
    }
    return x;
}
    
```

A	B	fiducial result	'possibly' semantics		'certainly' semantics	
		Max(A, B)	max(A, B)	max(B, A)	max(A, B)	max(B, A)
[0, 2]	[3, 6]	[3, 6]	[3, 6]	[3, 6]	[3, 6]	[3, 6]
[2, 4]	[3, 6]	[3, 6]	[3, 6]	[2, 4]	[2, 4]	[3, 6]
[4, 5]	[3, 6]	[4, 6]	[3, 6]	[4, 5]	[4, 5]	[3, 6]

too wide

incorrect

Relational identities

$$A \neq B \Leftrightarrow \neg(A = B)$$

$$A < B \Leftrightarrow \neg(A \geq B)$$

$$A = B \Leftrightarrow \neg(A < B \vee A > B)$$

implicitly relied on by else clause

(complementarity)

(totality)

None of these are equivalent for set-valued arguments with either 'possibly' or 'certainly' semantics.

(check counterexample $A = B = [0,1]$)

Let's fix this.

Representing ambiguity

What *should* ' $A < B$ ' mean for sets A, B ?

Remember the *set extension*:

$$A < B = \{(a < b) \mid a \in A, b \in B\}$$

one of \emptyset , $\{\text{false}\}$, $\{\text{true}\}$, or $\{\text{false}, \text{true}\}$

elements of the
powerset of $\{\text{false}, \text{true}\}$

Boolean powerset logic

Two-element Boolean algebra

$$\mathbb{B} := \{\text{false}, \text{true}\}$$

Powerset of \mathbb{B}

$$\mathcal{P}(\mathbb{B}) = \{\emptyset, \{\text{false}\}, \{\text{true}\}, \{\text{false}, \text{true}\}\}$$

$\mathcal{P}(\mathbb{B})$ is a *four-valued logic*:

- logical connectives \wedge , \vee , \neg given by set extension
- usual logical identities apply
(associativity, commutativity, distributivity, De Morgan's laws)

Relational identities

$$A \neq B \Leftrightarrow \neg(A = B)$$

$$A < B \Leftrightarrow \neg(A \geq B)$$

(complementarity)

$$A = B \Leftrightarrow \neg(A < B \vee A > B)$$

(totality)

All of these are equivalent for set-valued arguments with $\mathcal{P}(\mathbb{B})$ -valued relational predicates.

Implementing max with set-valued logic

$$\max(a, b) := \begin{cases} b & \text{if } a < b \\ a & \text{otherwise} \end{cases}$$

```
template <typename T>
T max(T a, T b) {
    T x;

    if (a < b) {

        x = b;
    }
    else {

        x = a;
    }
    return x;
}
```



```
template <typename T>
T max3(T a, T b) {
    auto x = T{ };
    auto c = (a < b);
    if (possibly(c)) {
        auto bc = constrain(b, c);
        assign_partial(x, bc);
    }
    if (possibly(!c)) {
        auto ac = constrain(a, !c);
        assign_partial(x, ac);
    }
    return x;
}
```


Implementing max with set-valued logic

$$\max(a, b) := \begin{cases} b & \text{if } a < b \\ a & \text{otherwise} \end{cases}$$

```
template <typename T>
T max(T a, T b) {
    T x;

    if (a < b) {

        x = b;
    }
    else {

        x = a;
    }
    return x;
}
```



```
template <typename T>
T max3(T a, T b) {
    auto x = T{ };
    auto c = (a < b);
    if (possibly(c)) {
        auto bc = constrain(b, c);
        assign_partial(x, bc);
    }
    if (possibly(!c)) {
        auto ac = constrain(a, !c);
        assign_partial(x, ac);
    }
    return x;
}
```

value initialisation

Implementing max with set-valued logic

$$\max(a, b) := \begin{cases} b & \text{if } a < b \\ a & \text{otherwise} \end{cases}$$

$\mathcal{P}(\mathbb{B})$ value

projection

possibly:

$\mathcal{P}(\mathbb{B}) \rightarrow \mathbb{B}$

$\mathcal{B} \mapsto (\text{true} \in \mathcal{B})$

```
template <typename T>
T max(T a, T b) {
    T x;

    if (a < b) {

        x = b;
    }
    else {

        x = a;
    }
    return x;
}
```



```
template <typename T>
T max3(T a, T b) {
    auto x = T{ };
    auto c = (a < b);
    if (possibly(c)) {
        auto bc = constrain(b, c);
        assign_partial(x, bc);
    }
    if (possibly(!c)) {
        auto ac = constrain(a, !c);
        assign_partial(x, ac);
    }
    return x;
}
```

\mathcal{B}	POSSIBLY(\mathcal{B})
\emptyset	false
{false}	false
{true}	true
{false, true}	true

Implementing max with set-valued logic

$$\max(a, b) := \begin{cases} b & \text{if } a < b \\ a & \text{otherwise} \end{cases}$$

```
template <typename T>
T max(T a, T b) {
    T x;

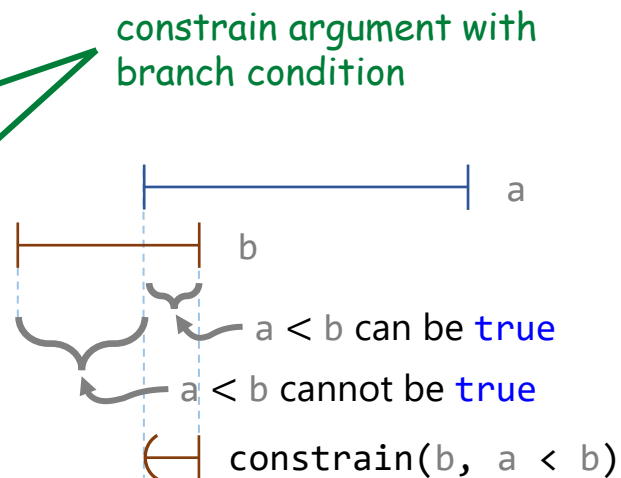
    if (a < b) {

        x = b;
    }
    else {

        x = a;
    }
    return x;
}
```



```
template <typename T>
T max3(T a, T b) {
    auto x = T{ };
    auto c = (a < b);
    if (possibly(c)) {
        auto bc = constrain(b, c);
        assign_partial(x, bc);
    }
    if (possibly(!c)) {
        auto ac = constrain(a, !c);
        assign_partial(x, ac);
    }
    return x;
}
```



Implementing max with set-valued logic

$$\max(a, b) := \begin{cases} b & \text{if } a < b \\ a & \text{otherwise} \end{cases}$$

```
template <typename T>
T max(T a, T b) {
    T x;

    if (a < b) {

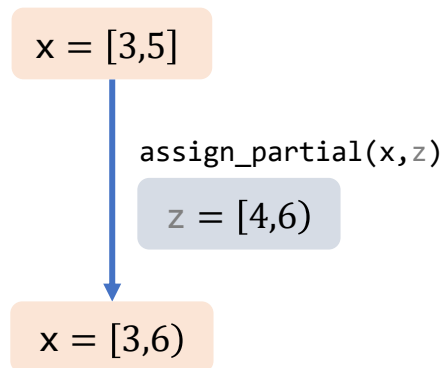
        x = b;
    }
    else {

        x = a;
    }
    return x;
}
```



```
template <typename T>
T max3(T a, T b) {
    auto x = T{ };
    auto c = (a < b);
    if (possibly(c)) {
        auto bc = constrain(b, c);
        assign_partial(x, bc);
    }
    if (possibly(!c)) {
        auto ac = constrain(a, !c);
        assign_partial(x, ac);
    }
    return x;
}
```

partial (additive)
assignment



Testing max3: empty set

```
template <typename T>
T max3(T a, T b) {
⇒ auto x = T{ };
⇒ auto c = (a < b);
⇒ if (possibly(c)) { ← false
    auto bc = constrain(b, c);
    assign_partial(x, bc);
  }
⇒ if (possibly(!c)) { ← false
    auto ac = constrain(a, !c);
    assign_partial(x, ac);
  }
⇒ return x;
⇒ }
```

x = ∅

a = [4,5]

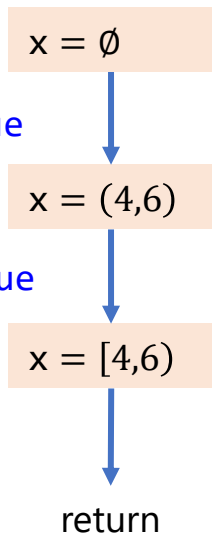
b = ∅

c = (a < b) = ∅

return

Testing max3: overlapping intervals

```
template <typename T>
T max3(T a, T b) {
  auto x = T{ };
  auto c = (a < b);
  if (possibly(c)) { ← true
    auto bc = constrain(b, c);
    assign_partial(x, bc);
  }
  if (possibly(!c)) { ← true
    auto ac = constrain(a, !c);
    assign_partial(x, ac);
  }
  return x;
}
```



$a = [4,5]$ $b = [3,6]$

$c = (a < b) = \{\text{false}, \text{true}\}$

$bc = \{b' | b' \in b, \text{POSSIBLY } a < b'\} = (4,6)$

$ac = \{a' | a' \in a, \text{POSSIBLY } \neg(a' < b)\} = [4,5]$

Testing max3: numbers

```
template <typename T>
T max3(T a, T b) {
  auto x = T{ };
  auto c = (a < b);
  if (possibly(c)) { ← true
    auto bc = constrain(b, c);
    assign_partial(x, bc);
  }
  if (possibly(!c)) { ← false
    auto ac = constrain(a, !c);
    assign_partial(x, ac);
  }
  return x;
}
```

x = 0

x = 3

return

a = 2

b = 3

c = (a < b) = true

bc = b

Optimal results for max3

domain type	A	B	fiducial result	experimental results	
			$\text{Max}(A, B)$	$\text{max3}(A, B)$	$\text{max3}(B, A)$
intervals	$[2, 4]$	$[3, 6]$	$[3, 6]$	$[3, 6]$	$[3, 6]$
intervals	$[4, 5]$	$[3, 6]$	$[4, 6]$	$[4, 6]$	$[4, 6]$
valids	$[2, 4]$	$(3, \infty)$	$(3, \infty)$	$(3, \infty)$	$(3, \infty)$
valids	$[2, 4]$	$[-\infty, 6]$	$[2, 6]$	$[2, 6]$	$[2, 6]$
valids	$[2, 4]$	$3](6$	$[2, \infty)$	$[2, \infty)$	$[2, \infty)$

intervals library

<https://github.com/mbeutel/intervals>

- portable C++20
- traditional interval arithmetic (closed intervals) with `float`, `double`
- interval arithmetic with discrete types (integers, iterators)
- $\mathcal{P}(\mathbb{B})$ logic, Boolean projections, powerset arithmetic (`bool`, `enum`)

Experimentally adapted for posits and valids using the posit/valid implementation of A. Schärfl [4] which is part of the *aarith* library (Keszöcze et al., 2021 [5]).

Bucketing

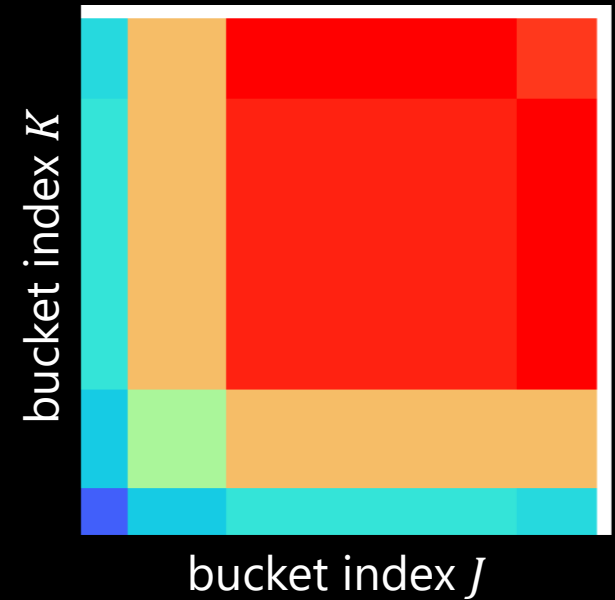
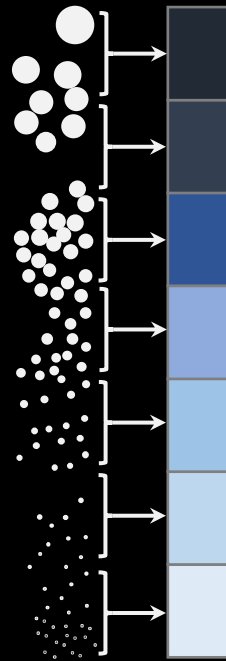
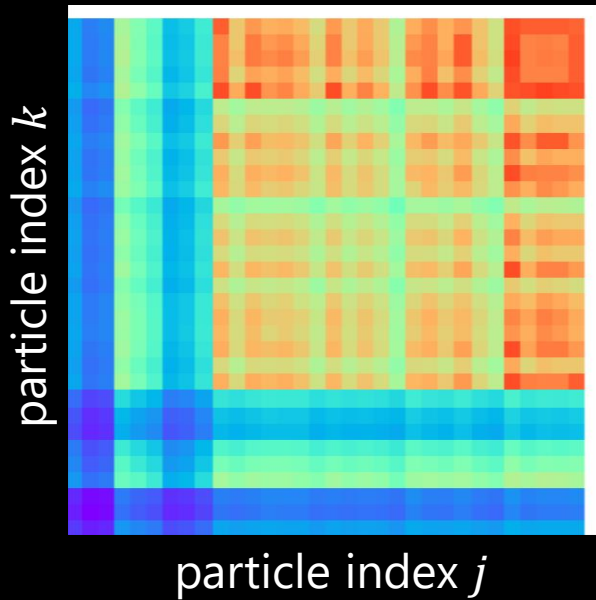
Beutel et al., in prep.

reuse interval-aware implementation of $\lambda(\mathbf{q}_j, \mathbf{q}_k)$

interaction rates
 $\lambda_{jk} := \lambda(\mathbf{q}_j, \mathbf{q}_k)$

group particles in buckets

interaction rate bounds
 $\Lambda_{JK} := \Lambda(\mathbf{Q}_J, \mathbf{Q}_K)$



Summary

For set-valued operands, relational predicates should be set-valued.

Functions with branches can be made *interval-aware* by following the proposed programming pattern.

Try it out: <https://github.com/mbeutel/intervals>

References

- [1] Andrews, S. M., Huang, J., Pérez, L. M., et al.: *The Disk Substructures at High Angular Resolution Project (DSHARP). I. Motivation, Sample, Calibration, and Overview*. ApJL, 869, L41 (2018)
- [2] Gustafson, J.L., Yonemoto, I.: *Beating Floating Point at its Own Game: Posit Arithmetic*. Supercomputing Frontiers and Innovations 4(2), 16 (2017)
- [3] Gustafson, J.L.: *Posit Arithmetic* (2017)
- [4] Schärrtl, A.: *Unums and Posits: A Replacement for IEEE 754 Floating Point?* M.Sc. thesis (2021)
- [5] Keszöcze, O., Brand, M., Witterauf, M., Heidorn, C., Teich, J.: *Aarith: an arbitrary precision number library*. In: Proceedings of the 36th Annual ACM Symposium on Applied Computing. pp. 529–534. SAC '21, Association for Computing Machinery, New York, NY, USA (2021)

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